

**QUANTITY**:

## **LINEAR SYSTEMS APPLICATION DATA FORM**

NAME:					EMAIL:						
COMPANY:											
ADDRESS:											
CITY:						STATE:	ZI	P:			
PHONE:											
AXIS NAME:											
Orientation:			Horizon	tal		Vertical	Ar	ngle to Horizo	ntal		
	PLICATION TYPE:										
TY	PICAL MOVE:	\/	NI -				0	V	NI -		
	Point to point?	Yes	No				Scanning?	Yes	No		
	Distance:			units:			Scanning speed:			units:	
	Move time:		units				Constant velocity +/-				
	Dwell time:	time: un					Data acquisi	ition frequenc	СУ		
	or:										
	Max speed:	ax speed:		units				Min speed:		units	
	Max acceleration:	Max acceleration:						Return speed:		units	
	Max travel:		units								
OPERATION:											
	How many hours p	er day?									
Move repeatabilit		:	units:				Move accura	acy:		units	
LOAD:											
	Moving weight ma	nass units			(do n	ot include o	coil mass)				
	Does above weight include motor mounting				veight?		Yes	No			
Opposing Force of		uring move forward			units		(Force during	g accel/decel	? Ye	es No)	
	Opposing Force du	uring move return			units		(Force during	g accel/decel	? Ye	es No)	
AMBIENT:											
	Max operating amb	pient temperature			units		Minimum operating ambient		ient tempera	iture	units
Will it work unde		vacuum	Yes	No			(if yes vacuu	ım level	units	)	
	Is this a clean roon	n environm	nent?	Yes	No		(If yes Class	)			
PO	WER AVAILABLE										
	VAC		VI	OC							
MC	OTOR PREFERENCE										
	AC [	OC	Servo		Stepper	Other					
DR	IVE										
	Type/Preference:										
	I/O:										
	Communication:										